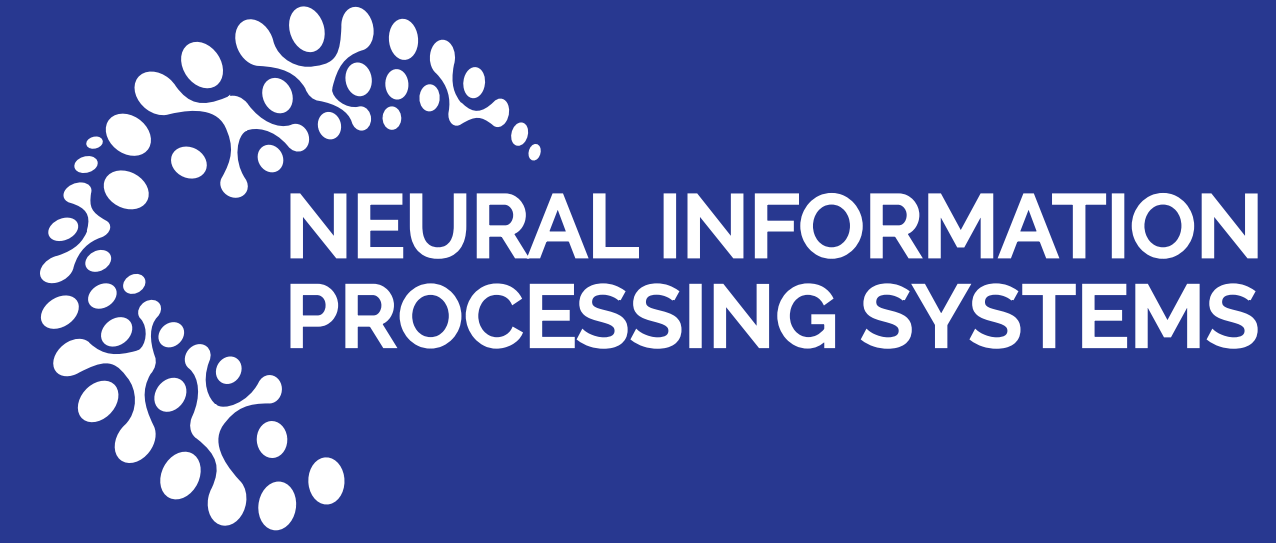


RELATIVE STABILITY TOWARD Diffeomorphisms INDICATES PERFORMANCE IN DEEP NETS

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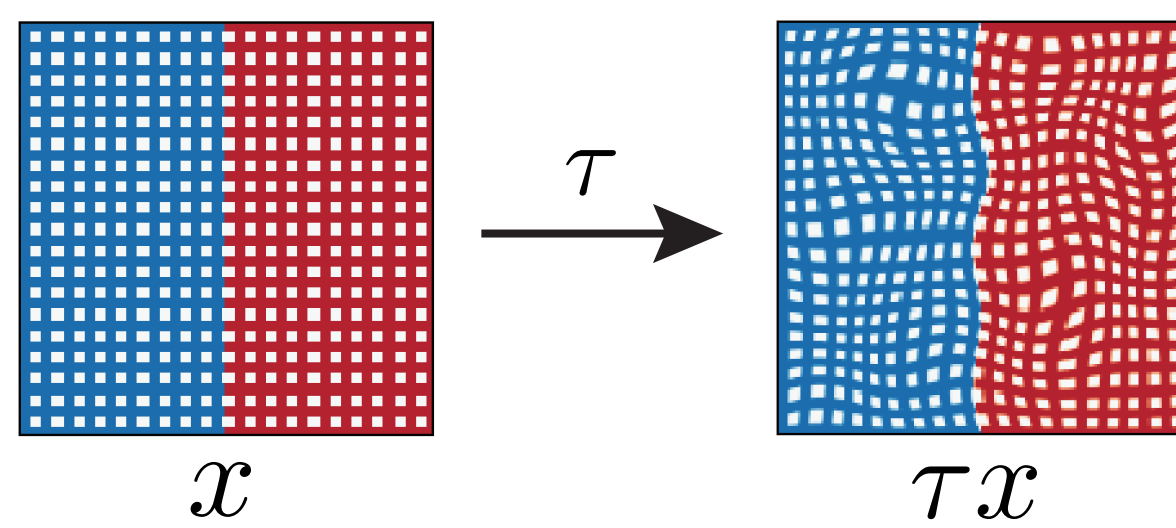
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MAX-ENTROPY Diffeomorphisms

Goal: define a distribution of *typical* diffeomorphisms of controlled magnitude.

NOTATION	
$x(s)$	input image intensity
$s = (u, v) \in [0, 1]^2$	(continuous) pixel position
τ	smooth deformation
$[\tau x](s) = x(s - \tau(s))$	deformed image
$\tau(s) = (\tau_u(s), \tau_v(s))$	displacement vector field



The **deformation amplitude** is measured by:

$$\|\nabla \tau\|^2 = \int_{[0,1]^2} (\nabla \tau_u)^2 + (\nabla \tau_v)^2 \, dudv. \quad (1)$$

We write each of the displacement fields in real Fourier basis and fix the picture frame not to be deformed (i.e. $\tau_u = \tau_v = 0$ if $u = 0, 1$ or $v = 0, 1$):

$$\tau_u = \sum_{i,j} C_{ij} \sin(i\pi u) \sin(j\pi v). \quad (2)$$

The Fourier coefficients C_{ij} are random variables and their distribution defines the one over displacement fields.

To determine it, we inject (2) into (1) and get:

$$\|\nabla \tau\|^2 = \frac{\pi^2}{4} \sum_{i,j} (C_{ij}^2 + D_{ij}^2) (i^2 + j^2).$$

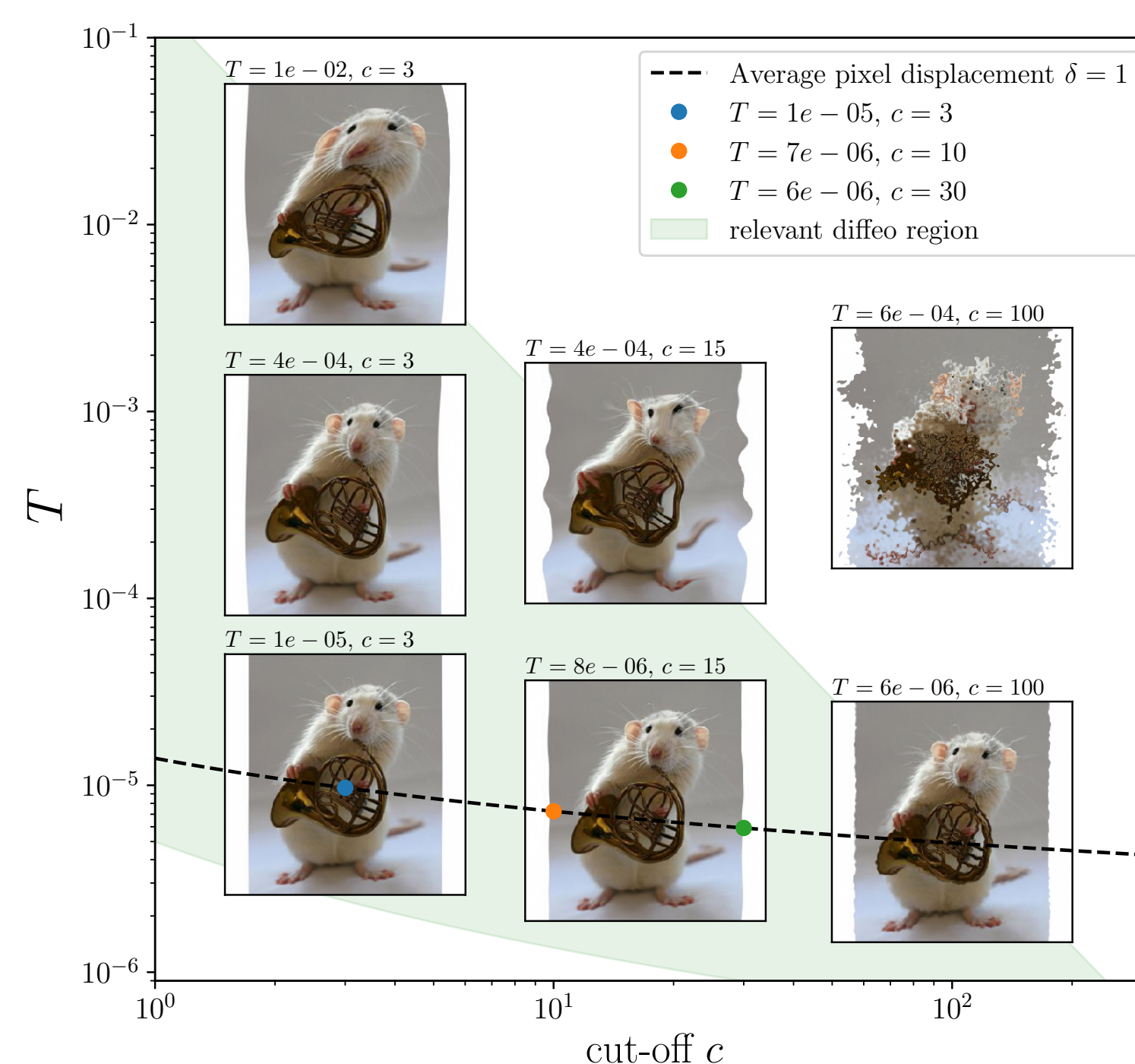
In order to control $\langle \|\nabla \tau\|^2 \rangle$, we introduce a **temperature** parameter T such that $\langle \|\nabla \tau\|^2 \rangle \propto T$. This is a *canonical ensemble* where the energy $\|\nabla \tau\|^2$ is a sum of quadratic random variables and the *equipartition theorem* applies: each term contributes equally to the sum - on average - fixing the variance of the Fourier coefficients:

$$\langle C_{ij}^2 \rangle = \frac{T}{i^2 + j^2}.$$

Finally, the distribution that **maximizes entropy** with a constraint on the variance is the **Gaussian**, hence

$$C_{ij} \sim \mathcal{N}\left(0, \frac{T}{i^2 + j^2}\right).$$

Figure: some sample of *max-entropy diffeomorphisms*.



RELATIVE STABILITY

Goal: establish if a **deep net** learns to become more stable to **diffeomorphisms** than to a **generic data transformation**.

NOTATION	
x	input image intensity
τ	smooth deformation
η	isotropic noise
f	network function
Moreover, we fix $\ \eta\ = \langle \ \tau x - x\ \rangle$	

We define the **relative stability to diffeomorphisms** as

$$R_f = \frac{\langle \|f(\tau x) - f(x)\|^2 \rangle_{x,\tau}}{\langle \|f(x + \eta) - f(x)\|^2 \rangle_{x,\eta}}.$$

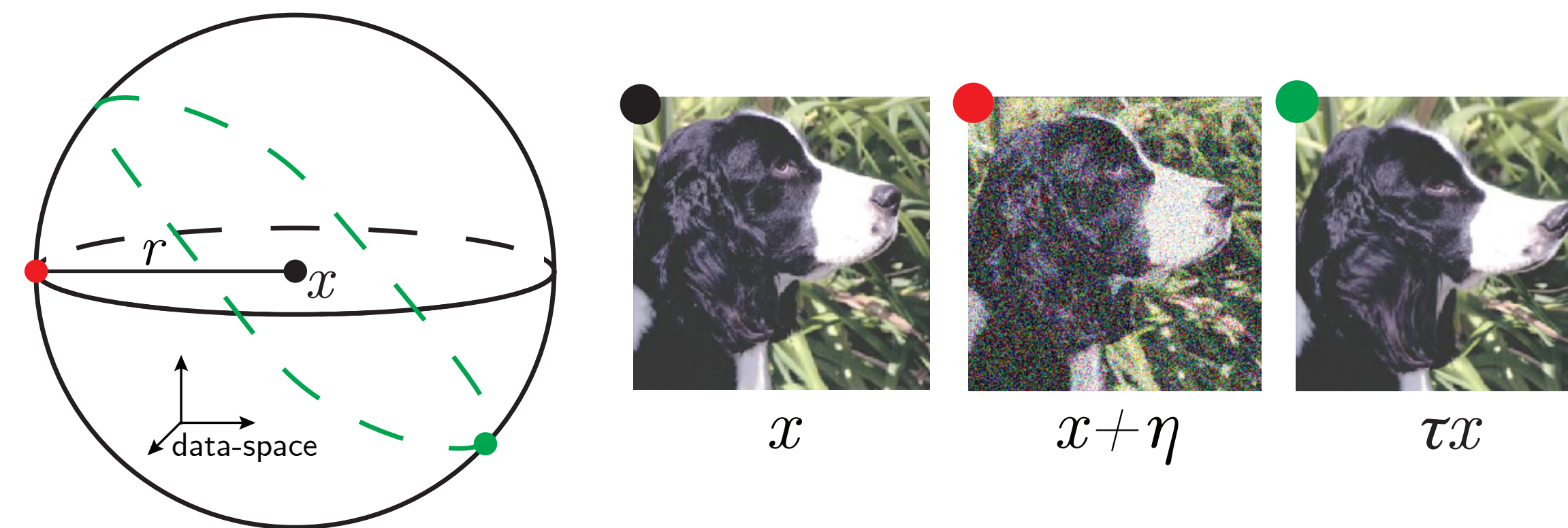
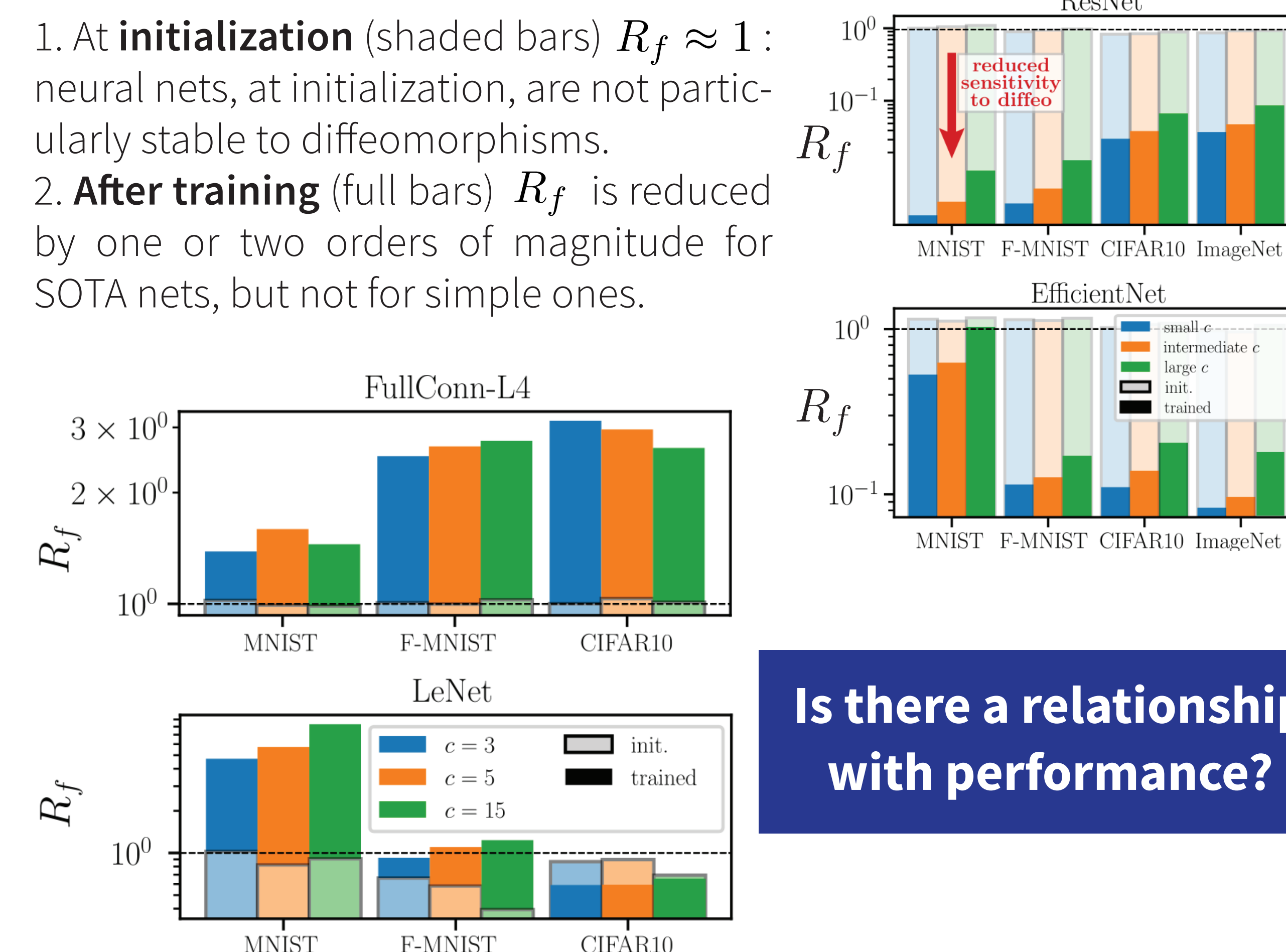


Figure: data-space around a data-point (illustrative). The relative stability to diffeomorphisms characterizes how a net f varies in the green directions, normalized by random ones - i.e. any point on the sphere, e.g. red dot.

DEEP NETS LEARN Diffeo INVARIANCE

1. At **initialization** (shaded bars) $R_f \approx 1$: neural nets, at initialization, are not particularly stable to diffeomorphisms.
2. **After training** (full bars) R_f is reduced by one or two orders of magnitude for SOTA nets, but not for simple ones.



Is there a relationship with performance?

IN SHORT

1. Why **deep nets** can classify images living in **high dimension**?
2. Do they do so by becoming **stable to diffeomorphisms**?
3. Previous empirical works are in support of a negative answer to (2.)

We revisit this question by

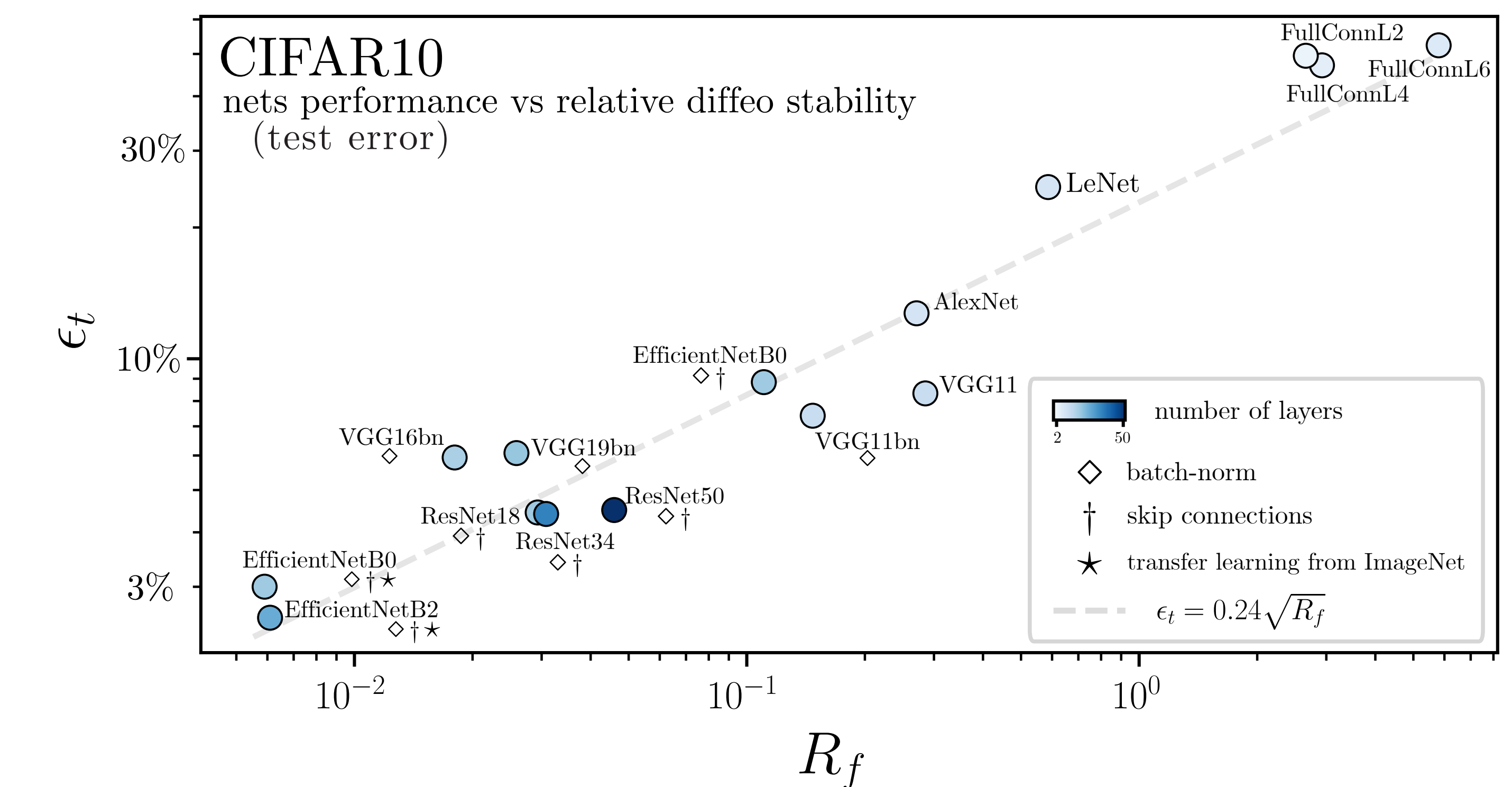
4. defining a **maximum-entropy distribution on diffeomorphisms**
5. finding that the **stability toward diffeomorphisms relative to that of generic transformations** R_f shows robust empirical behaviors across architectures and datasets.

We conclude that **relative diffeomorphisms stability**

6. **builds up with training** in SOTA nets
7. is important for obtaining good **performance**

Diffeo STABILITY AND PERFORMANCE

Relative stability shows a striking correlation with performance!



CONCLUSION

We have introduced a novel empirical framework to characterize how **deep nets become invariant to diffeomorphisms**. It is jointly based on a maximum-entropy distribution for diffeomorphisms, and on the realization that stability of these transformations relative to generic ones R_f strongly correlates to performance, instead of just the diffeomorphisms stability considered in the past.

Diffeomorphisms library: github.com/pcsl-epfl/diffeomorphism
Training SOTA nets: github.com/leonardopetrini/diffeo-sota
Pre-trained models: doi.org/10.5281/zenodo.5589869



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